GD600A Series

High-Performance Multi-drive VFD

















VITS



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Company Introduction

INVT (Shenzhen INVT Electric Co., Ltd) has been concentrating on industry automation and energy power since its foundation in 2002 and is committed to "Providing the best product and service to allow customers more competitiveness". INVT goes public in 2010 and is the first A-share listed company (002334) in Shenzhen Stock Exchange in the industry. At present, INVT owns 15 subsidiaries and more than 4500 employees, over 40 branches, forming a sales network covering more than 100 overseas countries and regions.

INVT has been awarded as the Key High-tech Enterprise of National Torch Plan based on mastering of key technologies in power electronics, auto control and IT. With business covering industry automation, electric vehicle, network power and rail transit, INVT has established 10 R&D centers nationwide, boasts more than 1400 patents and owns the first lab in the industry awarded ACT qualification from TÜV SÜD, UL-WTDP and CNAS National Lab. The industrial parks in Shenzhen and Suzhou aim to provide customers with advanced integrated product development design management, comprehensive product R&D test and auto informational production. The worldwide INVT branches and warranty service centers are ready to offer customers all-around back-ups including professional solutions, technical trainings and service support.

In the next decade, INVT will continue to take "Sincere Virtuous, Professional Aspiring" as our business philosophy, enhance core business sectors including industrial automation, electric vehicle, network power and rail transit based on the three major technologies in industry automation and energy power fields, and strive to become a leading, responsible and harmonic international professional group armed with proper product structure, leading technologies, efficient management, robust profitability and superior competitiveness.



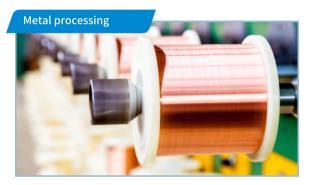
Product introduction

GD600A series high-performance multi-drive VFD is a common DC bus multi-drive system composed of rectifier unit(s) and inverter unit(s). It adopts a book-style unit structure and an integrated bus control mechanism, featuring high power density, flexible communication networking, and strong scalability, with unparalleled advantages.

- Integrated STO function
- Compatible with mainstream fieldbuses from 1MB to 100MB
- Integrated with torque, speed, and position control
- Capable of driving asynchronous induction motors, permanent magnet synchronous motors, and servo motors
- Outstanding dynamic response and control accuracy



GD600A can be widely applied to continuous production lines consisting of single or multiple machines with multi-motor drive configurations, typically used in metal processing, logistics machinery, printing and packaging, textile machinery, tissue machinery, and small-scale papermaking equipment.









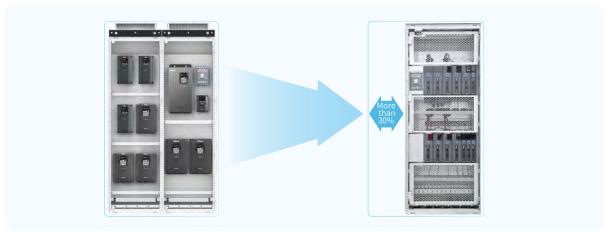




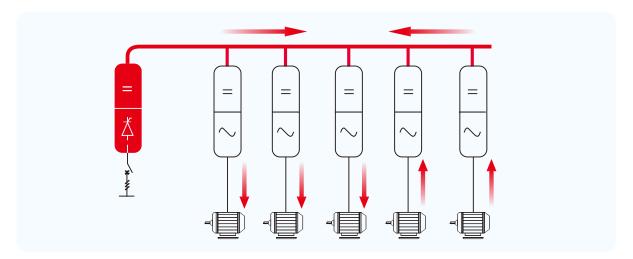
Multi-drive high-performance

• The common DC bus solution enables internal energy flow, enhances overall system electrica efficiency, and achieves up to 30% energy savings

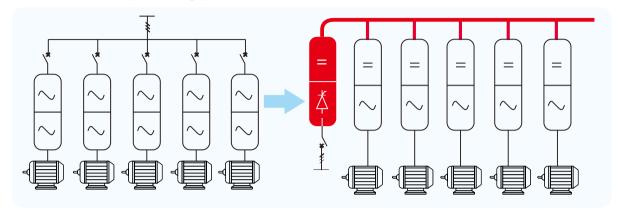




• Modular book-style design with uniform height and depth enables multiple units to be installed side by side compactly, saving more than 30% of cabinet space.



• The common DC bus solution utilizes a uniform power supply based on the rectifier unit, effectively reducing the number of main circuit switching devices, braking units, and redundant power cables, thereby lowering system costs.



Quick installation

Quick connection design for DC bus enables fast parallel operation, saving wiring labor and costs.

Optional DC external terminals address challenges of layered installation, maximizing cabinet space utilization.



• Provides integrated drive support for synchronous, asynchronous, and servo motors, facilitating equipment upgrades.

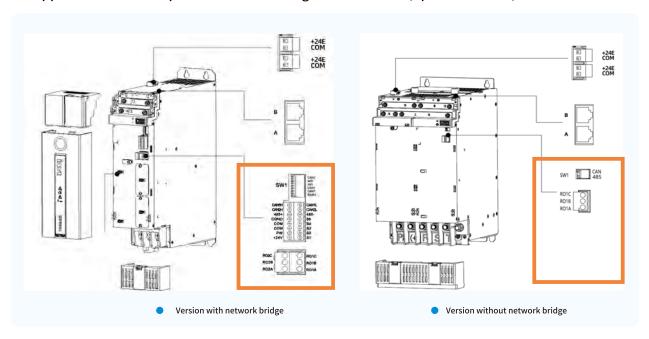


Product features

- Multiple types of rectifier units are available, meeting different requirements.
- Semi-controlled rectifier units come standard with network bridge functionality and support networking.
- Uncontrolled rectifier units are available in two versions—with or without network bridge.

| Product model | Rated power (kW) | Rectifier type | Network bridge function |
|---------------------|------------------|-----------------|-------------------------|
| GD600A-71-045-4-B | 45 | Semi-controlled | Standard |
| GD600A-71-160-4 | 160 | Semi-controlled | Standard |
| GD600A-71-355-4 | 355 | Semi-controlled | Standard |
| GD600A-61-022-4-B | 22 | Uncontrolled | Standard |
| GD600A-61-022-4-B-S | 22 | Uncontrolled | None |
| GD600A-61-110-4-B | 110 | Uncontrolled | Standard |
| GD600A-61-110-4-B-S | 110 | Uncontrolled | None |

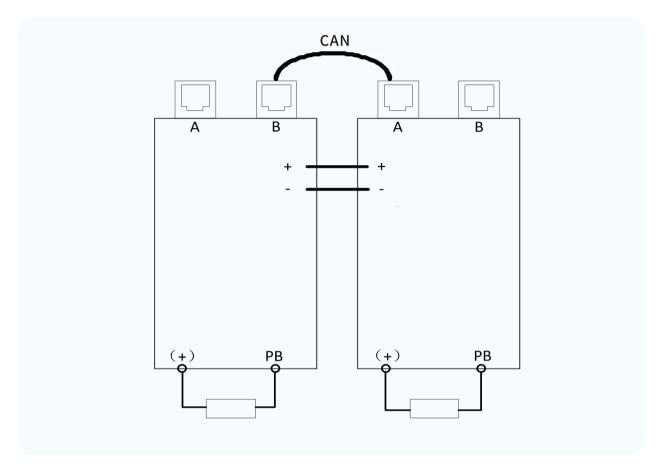
- The 110kW rectifier unit and lower are embedded with the built-in braking unit, saving the cost.
- Supports short-circuit protection for braking resistor cables (up to 10 meters).

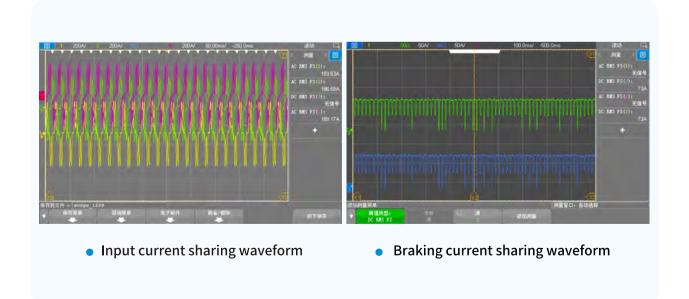


Note: The non-controlled rectifier unit must use its own configured network cable to connect to the inverter unit's RJ45 port for uploading fault information.



- Supports parallel connection of rectifier units without requiring input reactors, input current imbalance less than 10%.
- Built-in braking units support synchronous control, allowing two units to be connected in parallel with a current imbalance under 5%.





/ Performance enhancement

Strong adaptability to synchronous motors

- Self-adaptive loop parameters, no debugging required
- One-click auto-tuning for parameters

Control performance

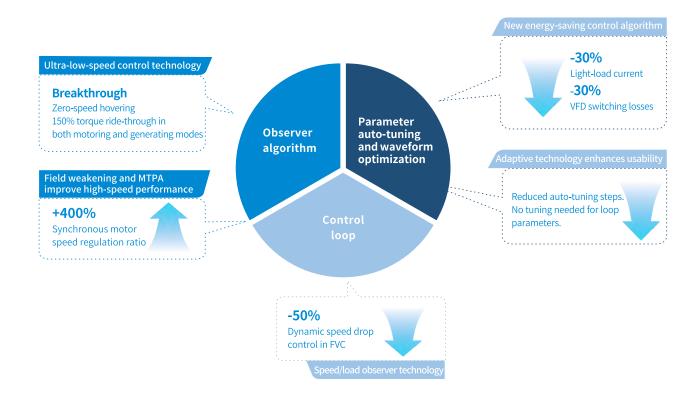
- Closed-loop vector control: dynamic speed drop < 0.25%
- Speed overshoot < 5%, torque response time < 5ms

Ultra-low-speed control technology

- Speed control ratio of permanent magnet synchronous motors exceeds 1:200
- Supports 150% torque ride-through for both asynchronous and synchronous motors in both motoring and generating modes.
- Supports 150% torque zero-speed hovering (short duration) for both asynchronous and synchronous motors

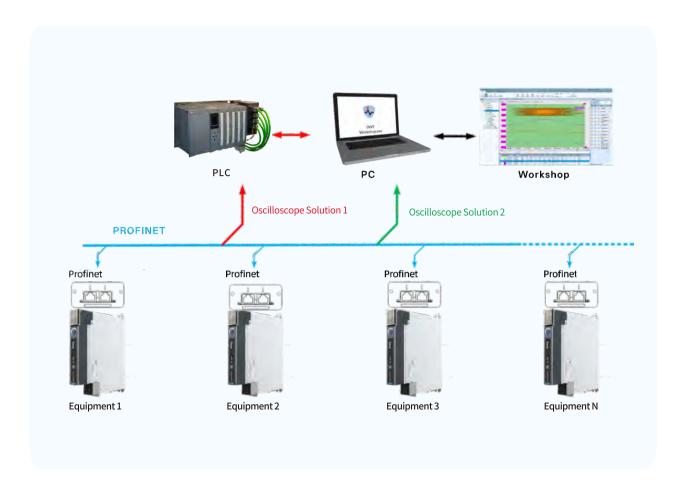
Green and low carbon

- Supports energy-saving control (MTPA), further reducing motor losses
- Both VF and vector control support new energy-saving algorithms, reducing light load current by 30%.
- Lower current harmonics (< 7%), resulting in less motor heating.
- Reduced noise levels.



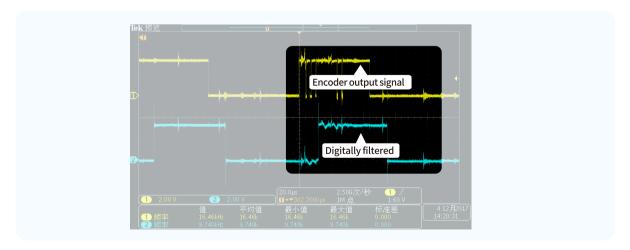


The PROFINET card supports waveform monitoring only with just one network cable.

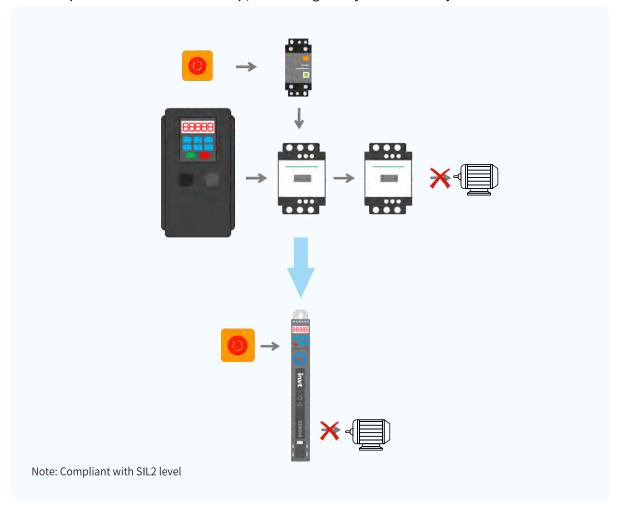


Safe and reliable

• The PG card adopts digital filtering technology, doubling anti-interference capability while ensuring stable reception of encoder signals over long distances.



• Comes standard with STO (Safe Torque Off) functionality. When the motor stops, torque output is cut off to prevent unintended startup, enhancing safety and reliability.



• The inverter unit is equipped with a built-in DC fuse, effectively preventing fault propagation to the system and significantly improving system stability.



• Independent air duct design effectively prevents dust, particles, and other contaminants from entering the inverter, avoiding arcing and short circuits. This enhances product reliability and extends service life.



Fully automated conformal coating process ensures more consistent and uniform coverage, significantly enhancing PCB protection.



• A comprehensive reliability testing system ensures product performance in the most demanding and complex application environments.

| Test category | Test name | Detailed categories |
|------------------------|-------------------|---|
| | | Packaging compression test |
| | | Packaging resonance scanning and dwell test |
| | | Packaging random vibration test |
| | Packaging test | Packaging drop test |
| | | Packaging rolling test |
| Mechanical reliability | | Packaging tilt drop test |
| testing | | Packaging inclined impact test |
| | Shock test | Half-sine wave shock test (under operating/non-operating state) |
| | SHOCK test | Trapezoidal wave shock test (under non-operating state) |
| | vel | Sinusoidal vibration test (under operating state) |
| | Vibration test | Random vibration test (under operating/non-operating state) |
| | | Low temperature storage test |
| | | High temperature storage test |
| | | Low temperature operating test |
| | Temperature test | High temperature operating test |
| | | Temperature gradient test |
| Climatic environmental | | Temperature shock test |
| reliability test | | Constant damp heat test |
| | Damp heat test | Cyclic damp heat test |
| | Callegrand | Continuous salt spray test |
| | Salt spray test | Cyclic salt spray test |
| | | Combined low-temperature and low-pressure test |
| | Low pressure test | Combined high-temperature and low-pressure test |

Remarks:

INVT is the first industrial control manufacturer in China to be awarded the ACT (Acceptance of Client's Testing) certification by TÜV SÜD. This certification signifies that TÜV SÜD officially recognizes the technical proficiency of INVT's laboratory, accepts the test data produced by this laboratory, and acknowledges the validity of the test reports issued.



Electric vibratory system



Low pressure test box (Left)
Constant temperature and humidity test box (Right)

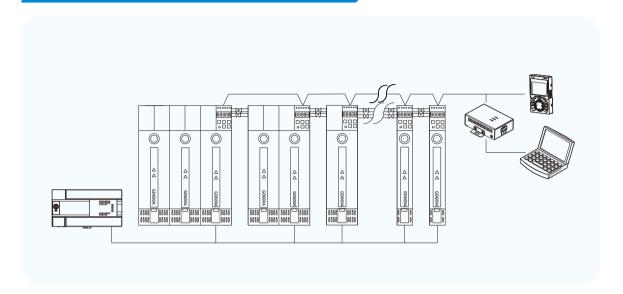


Natural convection test box (Left)
Hot and cold impact test box (Right)

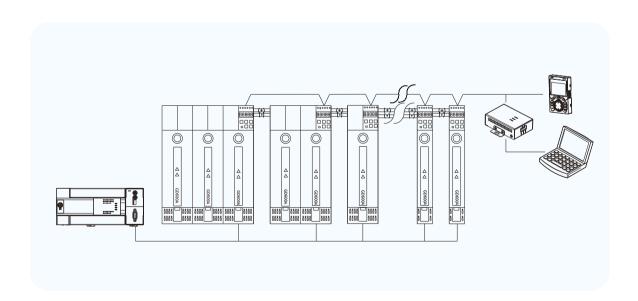


Seamless integration with automatic control system

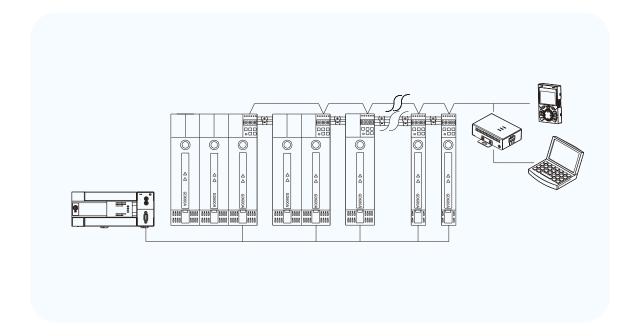
PLC + Standard Modbus fieldbus networking



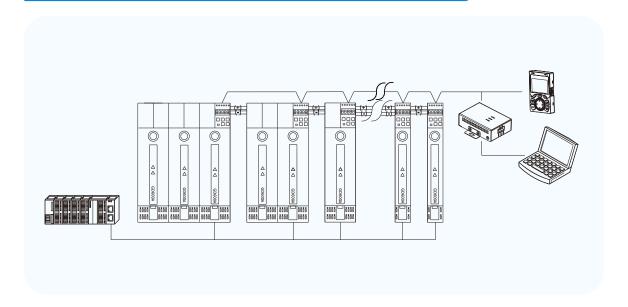
PLC + Standard CANopen fieldbus networking



PLC+ Optional PROFIBUS-DP fieldbus networking

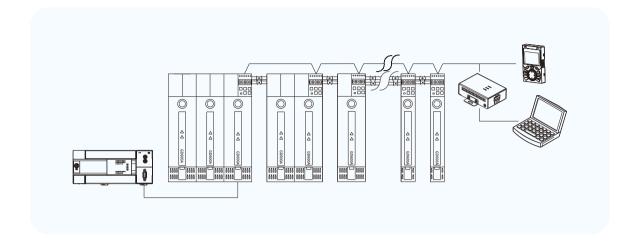


PLC+ Optional PROFINET/EtherCAT industrial Ethernet networking

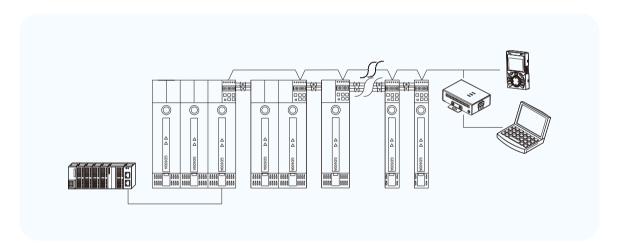




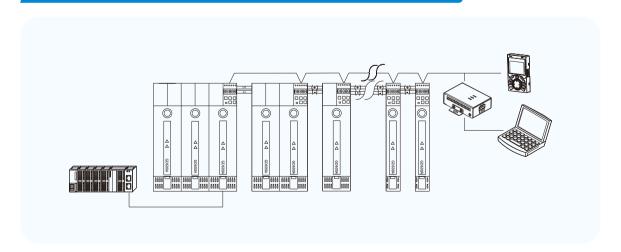
PLC+ Optional PROFIBUS-DP/CANopen network bridge networking



PLC+ Optional PROFINET/CANopen network bridge networking



PLC+ Optional EtherCAT/CANopen network bridge networking



/ Technical specifications

• Semi-controlled rectifier unit specifications

| Functio | n description | Specifications |
|---------------------------|---|---|
| Dannarianna | Input voltage (V) | AC 3PH 380V (-15%) – 440V (+10%); Rated voltage: 380V |
| Power input | Input frequency (Hz) | 50Hz or 60Hz; Allowed range: 47–53 (50Hz), 57–63 (60Hz) |
| Power output Power output | Output voltage (V) | 457Vdc-684Vdc |
| | Protection against abnormal input voltage | Protection against abnormal input voltage, such as input phase loss, input voltage too low, three-phase imbalance of input voltage |
| Protection functions | Braking circuit protection | Protection against braking circuit over current, braking resistor short-circuit, and braking-transistor direct connection |
| | Other protection functions | Such as protection against over voltage, undervoltage, and over temperature |
| | Digitalinput | Five regular inputs. Max frequency: 1kHz. Internal impedance: 3.3 k Ω . Resolution: no more than 2ms |
| | Relay output | Two programmable relay outputs RO1A: NO; RO1B: NC; RO1C: common RO2A: NO; RO2B: NC; RO2C: common Contact capacity: 3A/AC 250V, 1A/DC 30V |
| Peripheral interface | Communication interface | One RS485 communication interface, supporting the Modbus communication protocol Two CAN communication interfaces, of which CAN1 supports the CANopen communication protocol and CAN2 supports CAN master/slave control. |
| | Expansion interface | Two expansion interfaces, SLOT1 and SLOT2, supporting programmable cards, communication cards, I/O cards, and so on |
| | Installation method | Wall mounting or flange installation (not supported by 355kW) |
| | Operating ambient temperature | -10–50°C. Derating required above 40°C10–50°C. Derating required above 40°C. |
| | IP rating | IP00 |
| Other | Pollution degree | Degree 2 |
| Other | Cooling method | Forced air cooling |
| | Braking unit | Already built in the 45kW model; optional part (externally connected) for other models |
| | EMC filter | All the series meet the IEC61800-3 C3 requirements. Optional external filters can be used to meet the IEC61800-3 C2 requirements. |



• Uncontrolled rectifier unit specifications

| Functio | on description | Specifications | | |
|-------------------------|---|--|--|--|
| | Rectif | fier unit with network bridge | | |
| | Input voltage (V) | AC 3PH 380V (-15%) – 440V (+10%); Rated voltage: 380V | | |
| Power input | Input frequency (Hz) | 50Hz or 60Hz; Allowed range: 47–53 (50Hz), 57–63 (60Hz) | | |
| Power output | Output voltage (V) | 457Vdc-684Vdc | | |
| D | Protection against abnormal input voltage | Protection against input phase loss | | |
| Protection functions | Braking circuit protection | Protection against braking circuit over current, braking resistor short-circuit, and braking-transistor direct connection | | |
| | Other protection functions | Such as protection against overvoltage, undervoltage, and overtemperature | | |
| | Digital input | Five regular inputs. Max frequency: 1kHz. Internal impedance: 3.3 k Ω . Resolution: no more than 2ms | | |
| Peripheral | Relay output | Two programmable relay outputs RO1A: NO; RO1B: NC; RO1C: common RO2A: NO; RO2B: NC; RO2C: common Contact capacity: 3A/AC 250V, 1A/DC 30V | | |
| interface | Communication interface | One RS485 communication interface, supporting the Modbus communication protocol Two CAN communication interfaces, of which CAN1 supports the CANopen communication protocol and CAN2 supports CAN master/lave control. | | |
| | Expansion interface | Two expansion interfaces, SLOT1 and SLOT2, supporting programmable cards, communication cards, I/O cards, and so on | | |
| | Mounting method | Wall mounting or flange mounting | | |
| | Operating ambient temperature | -10–50°C. Derating required above 40°C. | | |
| | IP rating | IP00 | | |
| | Pollution degree | Degree 2 | | |
| Other | Cooling method | Forced air cooling | | |
| | Braking unit | Braking unit already built in the 22kW and 110kW models | | |
| | EMC filter | All the series meet the IEC61800-3 C3 requirements. Optional external filters can be used to meet the IEC61800-3 C2 requirements. | | |

| Functio | n description | Specifications | | |
|----------------------|---|--|--|--|
| | Rectifie | er unit without network bridge | | |
| | Input voltage (V) | AC 3PH 380V (-15%) – 440V (+10%); Rated voltage: 380V | | |
| Power input | Input frequency (Hz) | 50Hz or 60Hz; Allowed range: 47–53 (50Hz), 57–63 (60Hz) | | |
| Power output | Output voltage (V) | 457Vdc-684Vdc | | |
| | Protection against abnormal input voltage | Protection against input phase loss | | |
| Protection functions | Braking circuit protection | Protection against braking circuit overcurrent, braking resistor short-circuit, and braking transistor direct connection | | |
| | Other protection functions | Such as protection against overvoltage, undervoltage, and overtemperature | | |
| Peripheral - | Relay output | One programmable relay output RO1A: NO; RO1B: RC; RO1C: common terminal Contact capacity: 3A/AC 250V, 1A/DC 30V | | |
| interface | Communication interface | One CAN communication interface, supporting the rectifier unit and inverter unit internal CAN protocol | | |
| | Mounting method | Wall mounting or flange mounting | | |
| | Operating ambient temperature | -10–50°C. Derating required above 40°C. | | |
| | IP rating | IP00 | | |
| Other | Pollution degree | Degree 2 | | |
| | Cooling method | Forced air cooling | | |
| | Braking unit | Braking unit already built in the 22kW and 110kW models | | |
| | EMC filter | All the series meet the IEC61800-3 C3 requirements. Optional external filters can be used to meet the IEC61800-3 C2 requirements. | | |



• Inverter unit specifications

| Functio | on description | Specifications |
|-----------------------------|------------------------------|---|
| Power input | Input voltage (V) | 350Vdc~800Vdc |
| Danierant | Output voltage (V) | 0–0.7*Input voltage (V) |
| Power output | Output frequency (Hz) | 0~400Hz |
| | Control mode | Space vector modulation (SVM) control, sensorless vector control (SVC), and feedback vector control (FVC) |
| | Motor type | $A synchronous\ motor\ (AM)\ and\ permanent\ magnetic\ synchronous\ motor\ (SM)$ |
| | Speed regulation ratio | For AMs: 1: 200 (SVC) For SMs: 1: 200 (SVC) or 1: 1000 (FVC) |
| Technical | Speed control accuracy | \pm 0.2% (SVC); \pm 0.02% (FVC) |
| control | Speed fluctuation | ±0.3% (SVC) |
| performance | Torque response | < 20ms (SVC); < 5ms (FVC) |
| | Torque control accuracy | 10% (SVC); 5% (FVC) |
| | Starting torque | For AMs: 0.25Hz/150% (SVC) For SMs: 0.25Hz/150% (SVC); 0Hz/200% (FVC) |
| | Overload capacity | 150% rated current for 1 minute, 180% rated current for 10 seconds, 200% rated current for 1 second |
| | Frequency setting method | Settings can be implemented through digital, analog, pulse frequency, multi-step speed running, simple PLC, PID, Modbus communication, CANopen communication and so on. Settings can be combined and the setting channels can be switched. |
| Running control performance | Automatic voltage regulation | The output voltage can be kept constant although the bus voltage changes. |
| periormanee | Fault protection | Comprehensive protection functions, such as protection against overcurrent, overvoltage, undervoltage, overtemperature, and overload; protection against communication faults and position control faults |
| | Speed tracking restart | Enables smooth startup of a rotating motor. |
| | Digital input | Two inputs. AI1: 0(2)–10V / 0(4)–20mA; AI2: -10 – +10V Resolution: No more than 20mV |
| Peripheral | Analog output | One output. AO1: 0–10V/0–20mA |
| interface | Digital input | Four regular inputs. Max frequency: 1kHz. Internal impedance: 3.3 k Ω . Resolution: no more than 2ms |
| | Digital output | One Y terminal open collector output |

| Functio | n description | Specifications |
|----------------------|-------------------------------|---|
| | Relay output | Two programmable relay outputs RO1A: NO; RO1B: NC; RO1C: common RO2A: NO; RO2B: NC; RO2C: common Contact capacity: 3A/AC 250V, 1A/DC 30V One RS485 communication interface, supporting the Modbus |
| Peripheral interface | Communication interface | communication protocol. One CAN communication interface, for master/slave synchorization control. |
| | Expansion interface | Two expansion interfaces: SLOT1 and SLOT2 Supporting PG cards, programmable expansion cards, communication cards, I/O cards and so on |
| | Mounting method | Wall mounting or flange mounting |
| | Operating ambient temperature | -10–50°C. Derating required above 40°C. |
| Other | IP rating | IP00 |
| | Pollution degree | Degree 2 |
| | Cooling method | Forced air cooling |

Model selection

Model designation rules

GD600A-71-045-4-B-S









| Field | Symbol | Naming example |
|-------------------------------|----------|--|
| Product series | 1) | GD600A: High-performance multi-drive VFD |
| Product type | 2 | 71: Semi-controlled rectifier unit 61: Uncontrolled rectifier unit 51: Inverter unit |
| Powercode | 3 | 045:45kW |
| Voltage class | 4 | 4:400V |
| Braking unit | (5) | None: Empty by default B: Built-in braking unit |
| Order management number | 6 | Empty: With network bridge S: Without network bridge |

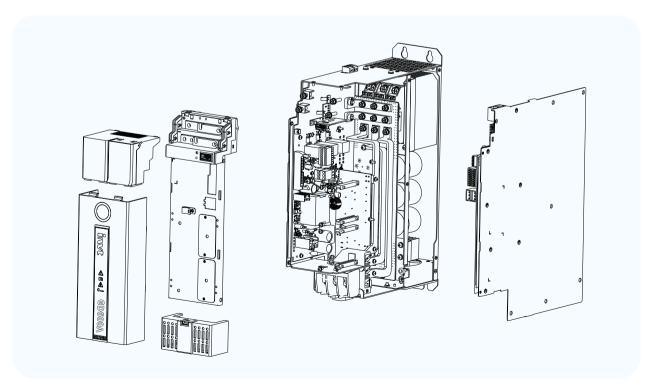
 $Note: The \ 160kW \ and \ 355kW \ rectifier units support the use of optional built-in input current detection module for data analysis, which needs$ to be customized.



Product overview

| Appearance | 0 [| | OI I was and | O a see a seed | | 0 1 | O I | O 1 - co | O I to 10 to | |
|-----------------------|------------|-------------|--------------|--|------------------|---------------|-------------|-------------|--|--|
| | | | Rectifie | erunit | | Inverter unit | | | | |
| Power (kW) | 22 | 45 | 110 | 160 | 355 | 1.5-7.5 | 11-37 | 45-75 | 90-160 | |
| Dimensions (W*H*D) | 50*400*350 | 100*400*350 | 200*400*350 | 300*400*350 | 180*805*423 | 50*400*350 | 100*400*350 | 200*400*350 | 300*400*350 | |
| Appearance | | | | and the state of t | | | | | | |
| Category | Com | ımunicatio | n card | PLC card | PG card I/O card | | | | | |

Rectifier unit module structure



Selection of rectifier units

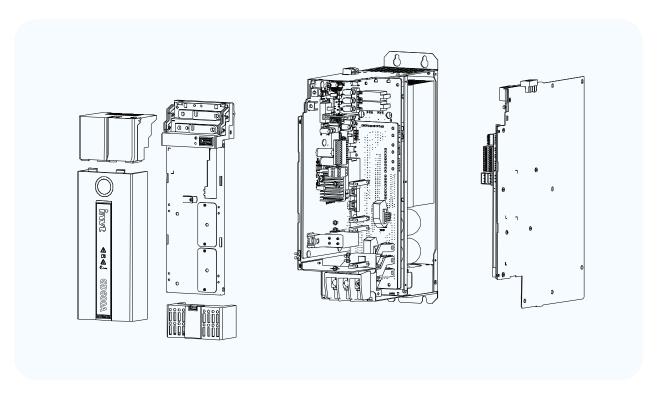
• Semi-controlled rectifier unit ratings

| Product model | Rated power (kW) | Power supply capacity (kVA) | Input current AC (A) | Output current DC (A) | Built-in busbar current carrying Capacity(A) | | | Recommended resistance | Network bridge function |
|-------------------|------------------------|--------------------------------------|----------------------------|-----------------------------|--|----|-----------------|---------------------------|-------------------------------|
| GD600A-71-045-4-B | 45 | 76 | 110 | 135 | 350 | 60 | Built-in | ≥13 | V |
| GD600A-71-160-4 | 160 | 215 | 320 | 380 | 350 | / | DBU100H-320-4 | ≥2.2 | √ |
| GD600A-71-355-4 | 355 | 433 | 625 | 766 | / | / | DBU100H-320-4×2 | ≥2.2x2 | V |

Uncontrolled rectifier unit ratings

| Product model | Rated power (kW) | Power supply capacity (kVA) | Input current AC (A) | Output current DC (A) | Built-in busbar current carrying Capacity(A) | | Recommended braking unit | Recommended resistance | Network bridge function |
|---------------------|------------------------|--------------------------------------|----------------------------|-----------------------------|--|-----|-----------------------------|---------------------------|-------------------------------|
| GD600A-61-022-4-B | 22 | 45 | 55 | 67 | 200 | 37 | Built-in | ≥17 | √ |
| GD600A-61-022-4-B-S | 22 | 45 | 55 | 67 | 200 | 37 | | ≥17 | × |
| GD600A-61-110-4-B | 110 | 169 | 225 | 276 | 350 | 145 | | ≥4.4 | √ |
| GD600A-61-110-4-B-S | 110 | 169 | 225 | 276 | 350 | 145 | | ≥4.4 | × |

/ Inverter unit module structure





/ Inverter unit selection

| In | put voltage range: 3 | 350Vdc-800Vdc Out | put voltage range: 0 | –0.7*Input voltage | |
|-----------------|----------------------|-------------------|----------------------|----------------------------------|---------------|
| Product model | Rated power | Input current DC | | Built-in busbar current carrying | Adapted motor |
| | (kW) | (A) | (A) | capacity (A) | kw |
| GD600A-51-1R5-4 | 1.5 | 3.6 | 3.7 | 200 | 1.5 |
| GD600A-51-2R2-4 | 2.2 | 5.5 | 5 | 200 | 2.2 |
| GD600A-51-004-4 | 4 | 9.6 | 9.5 | 200 | 4 |
| GD600A-51-5R5-4 | 5.5 | 14.2 | 14 | 200 | 5.5 |
| GD600A-51-7R5-4 | 7.5 | 19 | 18.5 | 200 | 7.5 |
| GD600A-51-011-4 | 11 | 26 | 25 | 350 | 11 |
| GD600A-51-015-4 | 15 | 33 | 32 | 350 | 15 |
| GD600A-51-018-4 | 18.5 | 40 | 38 | 350 | 18.5 |
| GD600A-51-022-4 | 22 | 47 | 45 | 350 | 22 |
| GD600A-51-030-4 | 30 | 62 | 60 | 350 | 30 |
| GD600A-51-037-4 | 37 | 79 | 75 | 350 | 37 |
| GD600A-51-045-4 | 45 | 97 | 92 | 350 | 45 |
| GD600A-51-055-4 | 55 | 121 | 115 | 350 | 55 |
| GD600A-51-075-4 | 75 | 158 | 150 | 350 | 75 |
| GD600A-51-090-4 | 90 | 206 | 180 | 350 | 90 |
| GD600A-51-110-4 | 110 | 240 | 215 | 350 | 110 |
| GD600A-51-132-4 | 132 | 288 | 260 | 350 | 132 |
| GD600A-51-160-4 | 160 | 350 | 305 | 350 | 160 |

/ Optional expansion cards

| Expansion card type | Model | Category | Specifications | | | | |
|---------------------|--------------|--|---|--|--|--|--|
| | EC-PG705-12B | Multi-function incremental PG card | Supports 5V/12V incremental encoders with differential, push-pull, and open-collector ABZ signals,up to 200 kHz. Supports pulse + direction command, up to 200kHz, and 5V differential output with 1–255 \times frequency multiplication. | | | | |
| | EC-PG704 | Resolver PG card | Supports differential pulse/direction inputs up to 200kHz; provides 5V differential output with 2^n (1–255 \times) multiplication. | | | | |
| | EC-PG707-24 | 24V incremental PG card | Supports 24V incremental encoders with differential, push-pull, and open-collector ABZ signals, up to 200kHz. | | | | |
| | EC-PG708-24 | Absolute encoder SSI communication PG card | Supports 24V incremental encoders with differential, push-pull, and open-collector ABZ signals, up to 400kHz. Supports SSI signal, 5V differential input, interrupted clock signal synchronization, with clock frequency up to 700kHz Supports frequency-division output with division ratios from 1 to 255. | | | | |
| PG card | EC-PG705-24 | | 1. Encoder interface: compatible with 24V push-pull, open collector, and differential signals, up to 400kHz 2. Pulse reference: compatible with 24V push-pull, open collector, and differential signals, up to 400kHz 3. Frequency-divided output: Supports open-collector output; external pull-up resistor required at the input side. Supports frequency division with division ratios from 1 to 255, configurable via P20.16 or P24.16. Supports frequency-division output source selection, configurable via P20.17 or P24.17. | | | | |
| | EC-TX703 | PROFIBUS-DP communication card | PROFIBUS protocol, 9.6kbps–12Mbps | | | | |
| | EC-TX709 | PROFINET communication card | Uses the PROFINET protocol and 100Mbps full-duplex operation. | | | | |
| 5 | EC-TX704 | Host controller card | Uses INVT internal Ethernet protocol to support INVT Studio monitoring. | | | | |
| Communication card | EC-TX708 | EtherCAT communication card | Uses the EtherCAT protocol to function as an EtherCAT slave. Provides two real-time industrial Ethernet interfaces, and supports 100Mbit/s full-duplex operation. | | | | |
| Programmable card | EC-PC701-02 | Programmable expansion card | Supports three programming languages—IL (Instruction List), LD (Ladder Diagram), and SFC (Sequential Function Chart); features 16K steps of user program memory and 8K words of data memory (D registers). | | | | |
| IO card | EC-10702 | IO card | Supports two digital inputs, one analog input, one analog output, one relay output, and supports temperature sensing with four sensor types: KTY84-130, PT100, PT1000, and NTC. | | | | |



/ Selection of structural components

| Name | Illustration | Model/Ordering code | Applicable model | | | | |
|--------------------------------------|--------------|------------------------|---|--|--|--|--|
| | | GD600-CON1 | Current-carrying capability: 100A; applicable to 1.5–7.5kW inverter units. | | | | |
| External DC connection terminal | | GD600-CON2 | Current-carrying capability: 200A; applicable to 45kW and 160kW rectifier units and 11–75kW inverter units. | | | | |
| External LCD keypad | | SOP-600 | All rectifier and inverter units | | | | |
| USB-RS485 communication module | | EC-TM485-USB | Used to connect the rectifier unit to the upper computer | | | | |
| | | GD600-SH1 | Shield bracket, 50mm, applicable to 1.5–7.5kW inverter units and 22kW rectifier unit. | | | | |
| Shield bracket | 0 0 0 0 | GD600-SH2 | Shield bracket, 100mm, applicable to 11–37kW inverter units and 45kW rectifier unit. | | | | |
| | 3 15 | GD600-SH3 | Shield bracket, 200mm, applicable to 45–75 kW inverter units. | | | | |
| | | GD600-SH4 | Shield bracket, 300mm, applicable to 90–160 kW inverter units. | | | | |
| | | GD600-FLAN1 | Mounting bracket, 50mm, applicable to 1.5–7.5kW inverter units and 22kW rectifier unit. | | | | |
| Flange-type | 0 0 | GD600-FLAN2 | Mounting bracket, 100mm, applicable to 11–37kW inverter units and 45kW rectifier unit. | | | | |
| mounting bracket | t | GD600-FLAN3 | Mounting bracket, 200mm, applicable to 45–75kW inverter units and 110kW rectifier units. | | | | |
| | | GD600-FLAN4 | Mounting bracket, 300mm, suitable for 90–160 kW inverter units and 160kW rectifier units. | | | | |
| | | GD600-AD1 | Air baffle, 50mm, applicable to 1.5–7.5kW inverter units and 22kW rectifier units. | | | | |
| Air baffle | | GD600-AD2 | Air baffle, 100mm, applicable to 11–37kW inverter units and 45kW rectifier unit. | | | | |
| All ballle | | GD600-AD3 | Air baffle, 200mm, applicable to 45–75kW inverter units and 110kW rectifier units. | | | | |
| | | GD600-AD4 | Mounting bracket, 300mm, applicable to 90–160 kW inverter units and 160kW rectifier unit. | | | | |



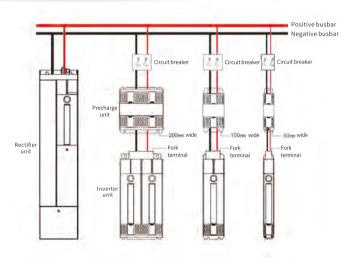
/ Main circuit accessory selection

| Туре | Product model | Reactor | Filter | |
|----------------|-----------------------|-----------------|----------------|--|
| | GD600A-61-022-4-B(-S) | GDL-ACL0051-4AL | FLT-P04065L-B | |
| | GD600A-71-045-4-B | GDL-ACL0110-4AL | FLT-P04100L-B | |
| Rectifier side | GD600A-61-110-4-B(-S) | GDL-ACL0220-4AL | FLT-P04240L-B | |
| | GD600A-71-160-4 | GDL-ACL0330-4AL | FLT-P04400L-B | |
| | GD600A-71-355-4 | GDL-ACL0580-4AL | FLT-P04800L-B | |
| | GD600A-51-1R5-4 | GDL-OCL0005-4CU | ELT LOMOOCL D | |
| | GD600A-51-2R2-4 | GDL-OCL0006-4CU | FLT-L04006L-B | |
| | GD600A-51-004-4 | GDL-OCL0010-4CU | FLT L0401CL B | |
| | GD600A-51-5R5-4 | GDL-OCL0014-4CU | FLT-L04016L-B | |
| | GD600A-51-7R5-4 | GDL-OCL0020-4CU | FLT-L04032L-B | |
| | GD600A-51-011-4 | GDL-OCL0025-4CU | FL1-L04032L-D | |
| | GD600A-51-015-4 | GDL-OCL0035-4AL | FLT-L04045L-B | |
| | GD600A-51-018-4 | GDL-OCL0040-4AL | 121 2040432 8 | |
| Inverter side | GD600A-51-022-4 | GDL-OCL0050-4AL | FLT-L04065L-B | |
| | GD600A-51-030-4 | GDL-OCL0060-4AL | 1 E1-E04003E-D | |
| | GD600A-51-037-4 | GDL-OCL0075-4AL | FLT-L04100L-B | |
| | GD600A-51-045-4 | GDL-OCL0092-4AL | 1 [1-[0-100[-] | |
| | GD600A-51-055-4 | GDL-OCL0115-4AL | FLT-L04150L-B | |
| | GD600A-51-075-4 | GDL-OCL0150-4AL | TET EUTISUE D | |
| | GD600A-51-090-4 | GDL-OCL0220-4AL | FLT-L04240L-B | |
| | GD600A-51-110-4 | GDL-OCL0220-4AL | FLT-L04240L-B | |
| | GD600A-51-132-4 | GDL-OCL0265-4AL | FLT-L04240L-B | |
| | GD600A-51-160-4 | GDL-OCL0330-4AL | FLT-L04400L-B | |

/ BUB selection



BUB600 series precharge unit is a DC precharging device designed for use with the inverter units of the GD600A series VFDs. When used in conjunction with a circuit breaker and external DC bus terminals, it enables independent power-up and power-down operations of the inverter unit, allowing convenient inverter unit replacement without interrupting the power supply to the rectifier.

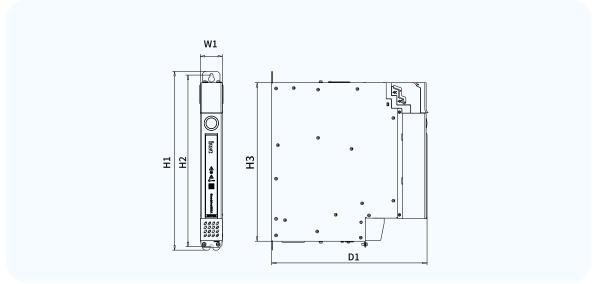


System schematic diagram

| Inverter unit | Matching BUB model | Recommended circuit breaker rated current (A) |
|-----------------|--------------------|---|
| GD600A-51-1R5-4 | BUB600-7R5-4 | 40 |
| GD600A-51-2R2-4 | BUB600-7R5-4 | 40 |
| GD600A-51-004-4 | BUB600-7R5-4 | 40 |
| GD600A-51-5R5-4 | BUB600-7R5-4 | 40 |
| GD600A-51-7R5-4 | BUB600-7R5-4 | 40 |
| GD600A-51-011-4 | BUB600-037-4 | 80 |
| GD600A-51-015-4 | BUB600-037-4 | 80 |
| GD600A-51-018-4 | BUB600-037-4 | 80 |
| GD600A-51-022-4 | BUB600-037-4 | 80 |
| GD600A-51-030-4 | BUB600-037-4 | 125 |
| GD600A-51-037-4 | BUB600-037-4 | 125 |
| GD600A-51-045-4 | BUB600-075-4 | 200 |
| GD600A-51-055-4 | BUB600-075-4 | 200 |
| GD600A-51-075-4 | BUB600-075-4 | 315 |

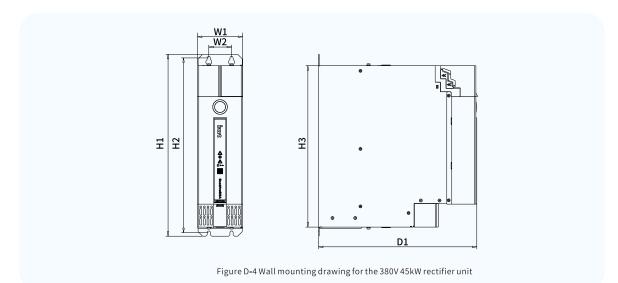
Mounting dimensions

• Wall mounting dimensions (for rectifier unit)



| Model | 01 | utline di (m | mension m) | S | Mounting hole spacing (mm) | | | Mounting hole diameter (mm) | Weight (kg) |
|-----------------------|-----|-----------------|---------------|-----|----------------------------|----|----|-----------------------------|----------------|
| | H1 | Н3 | W1 | D1 | H2 | W2 | W3 | didiffecer (fiffi) | (1.67 |
| GD600A-61-022-4-B(-S) | 400 | 355 | 50 | 350 | 384 | - | - | Ф7 | 4.7 |

Table D-1 Wall mounting dimensions for the 380V 22kW uncontrolled rectifier unit



| Outline dimensions Model (mm) | | | | | | ing hole s (mm) | spacing | Mounting hole diameter (mm) | |
|----------------------------------|-----|-----|-----|-----|-----|--------------------|---------|-----------------------------|------|
| | H1 | Н3 | W1 | D1 | H2 | W2 | W3 | diameter (iiiii) | (kg) |
| GD600A-71-045-4-B | 400 | 355 | 100 | 350 | 384 | 50 | - | Ф7 | 9 |

Table D-2 Wall mounting dimensions for the 380V 45kW rectifier unit

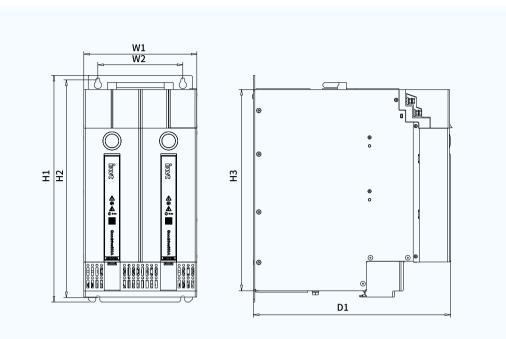
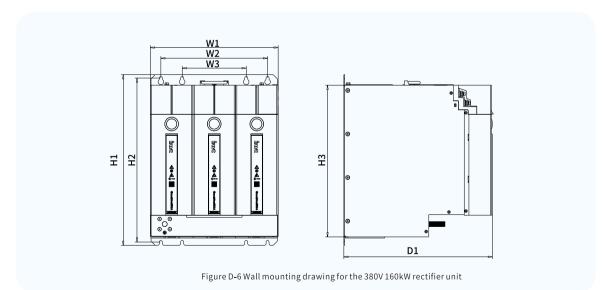


Figure D-5 Wall mounting drawing for the 380V 110kW uncontrolled rectifier unit

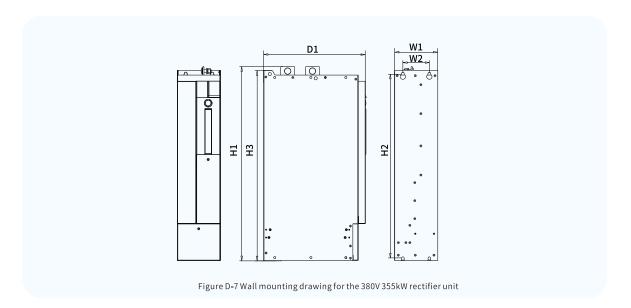
| Model | O | | imensior nm) | ıs | Mounting hole spacing (mm) | | | Mounting hole diameter (mm) | Weight (kg) |
|-----------------------|-----|-----|-----------------|-----|----------------------------|-----|----|-----------------------------|----------------|
| | H1 | Н3 | W1 | D1 | H2 | W2 | W3 | diameter (iiiii) | (ng) |
| GD600A-61-110-4-B(-S) | 400 | 355 | 200 | 350 | 384 | 150 | - | Ф7 | 16.8 |

 ${\sf Table\,D-3\,Wall\,mounting\,dimensions\,for\,the\,380V\,110kW\,uncontrolled\,rectifier\,unit}$



| Outline dimensions Model (mm) | | | | | | ng hole s (mm) | pacing | Mounting hole diameter (mm) | Weight (kg) |
|--------------------------------|-----|-----|-----|-----|-----|-------------------|--------|-----------------------------|----------------|
| | H1 | Н3 | W1 | D1 | H2 | W2 | W3 | diameter (mm) | (kg) |
| GD600A-71-160-4 | 400 | 355 | 300 | 350 | 384 | 250 | 150 | Ф7 | 28 |

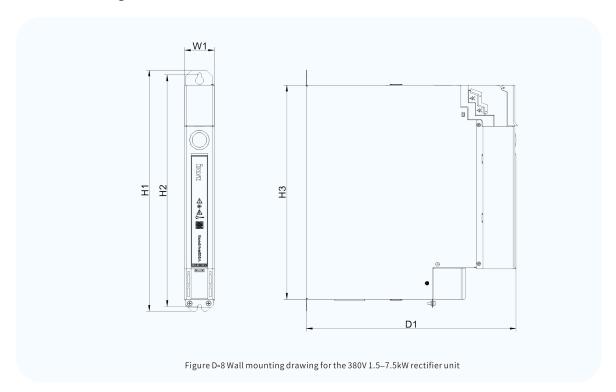
Table D-4 Wall mounting dimensions for the 380V 160kW rectifier unit

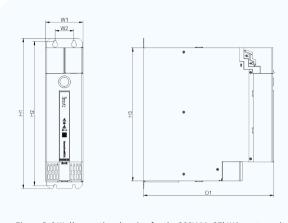


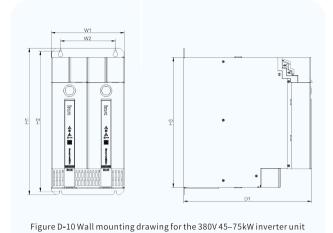
| Model | Outline dimensions el (mm) | | | | | ng hole s (mm) | pacing | Mounting hole diameter (mm) | Weight (kg) |
|-----------------|-------------------------------|-----|-----|-----|-------|-------------------|--------|--------------------------------|----------------|
| | H1 | Н3 | W1 | D1 | H2 | W2 | W3 | diameter (mm) | (ng) |
| GD600A-71-355-4 | 805 | 790 | 180 | 423 | 767.5 | 110 | - | Ф11 | 42.6 |

Table D-5 Wall mounting dimensions for the 380V 355kW rectifier unit

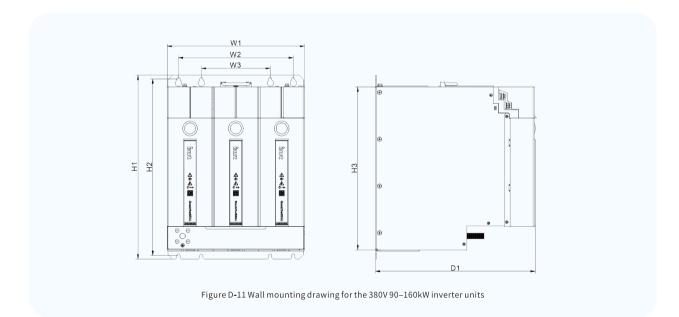
• Wall mounting dimensions (for inverter unit)











| Model | Outline dimensions (mm) | | | | Mounti | ng hole sp (mm) | oacing | Mounting hole | Weight |
|-----------------------|----------------------------|-----|-----|-----|--------|--------------------|--------|---------------|--------|
| | H1 | Н3 | W1 | D1 | H2 | W2 | W3 | diameter (mm) | (kg) |
| GD600A-51-(1R5-7R5)-4 | 400 | 355 | 50 | 350 | 384 | - | - | Ф7 | 4 |
| GD600A-51-(011-037)-4 | 400 | 355 | 100 | 350 | 384 | 50 | - | Ф7 | 9 |
| GD600A-51-(045-075)-4 | 400 | 355 | 200 | 350 | 384 | 150 | - | Ф7 | 18 |
| GD600A-51-(090-160)-4 | 400 | 355 | 300 | 350 | 384 | 250 | 150 | Ф7 | 28 |

Figure D-8 Wall mounting drawing for the 380V 1.5–160kW inverter units

• Flange mounting dimensions (rectifier and inverter units in parallel)

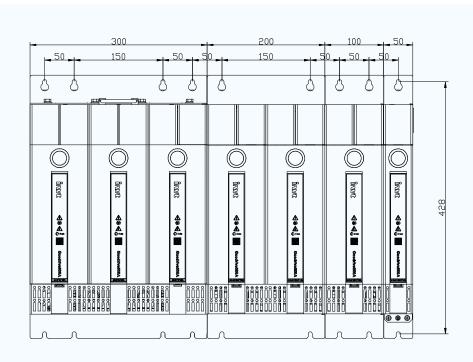


Figure D-12 Flange mounting drawing for the 380V rectifier and inverter units

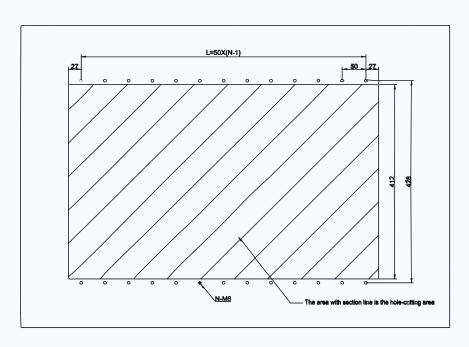
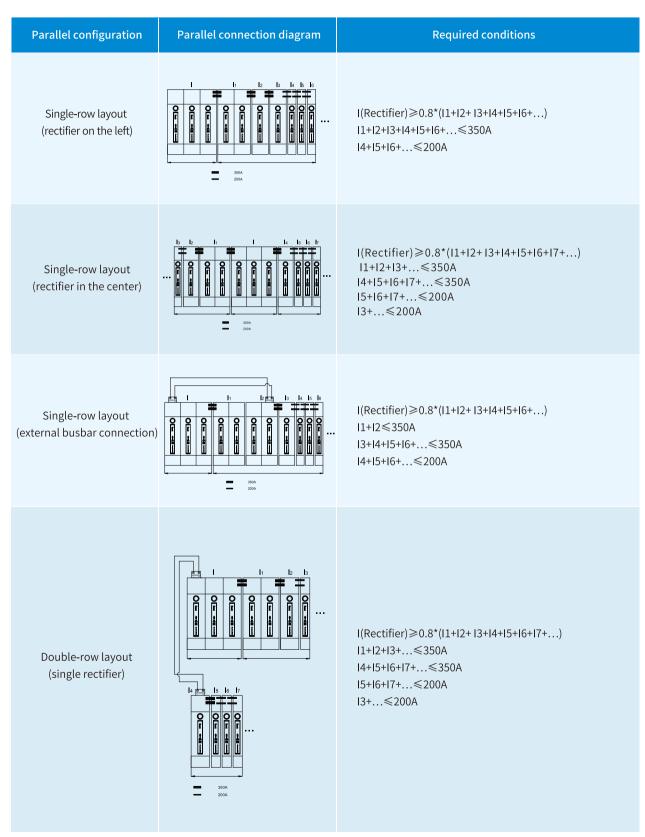


Figure D-13 Flange mounting drawing for the 380V rectifier and inverter units

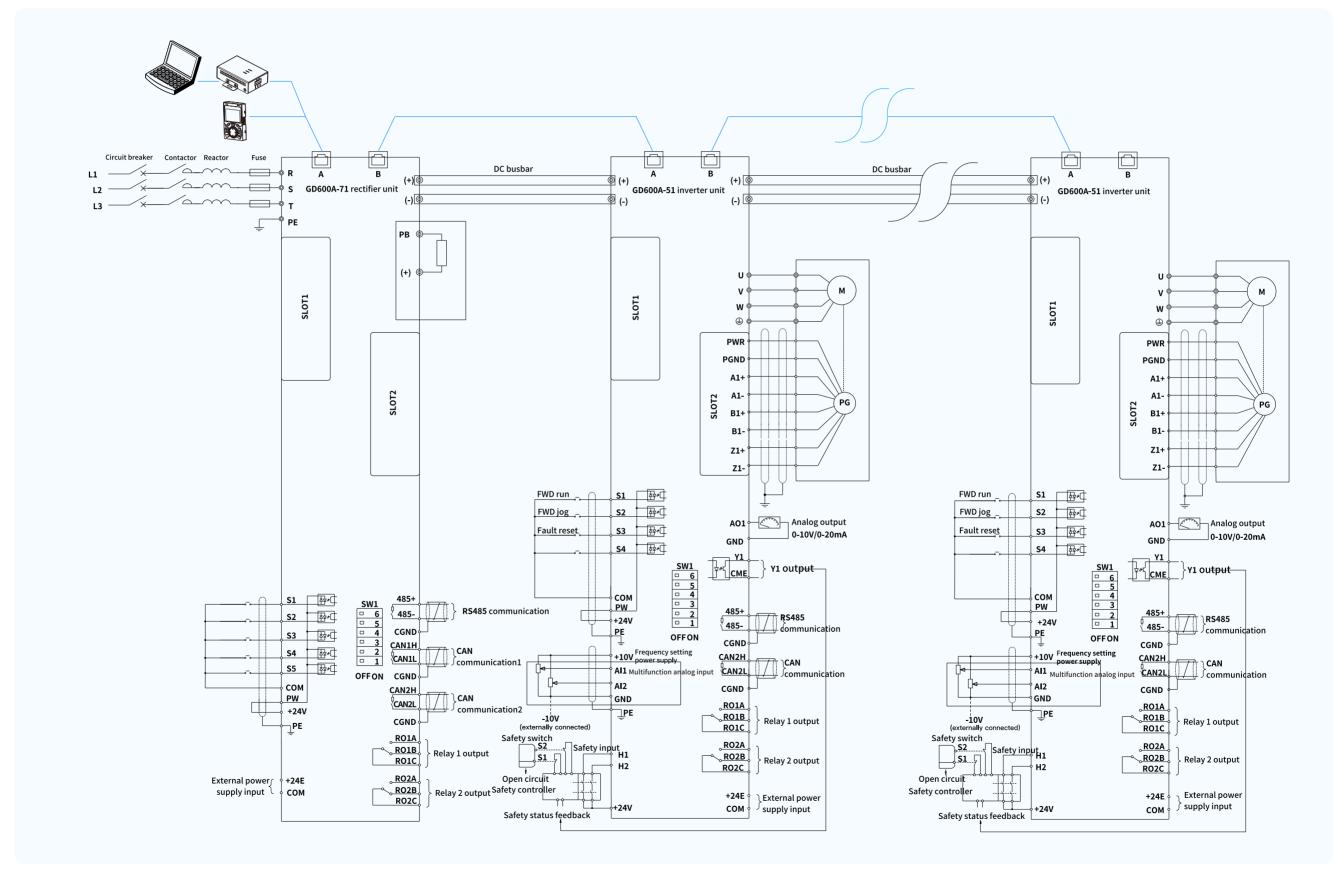


Parallel connection



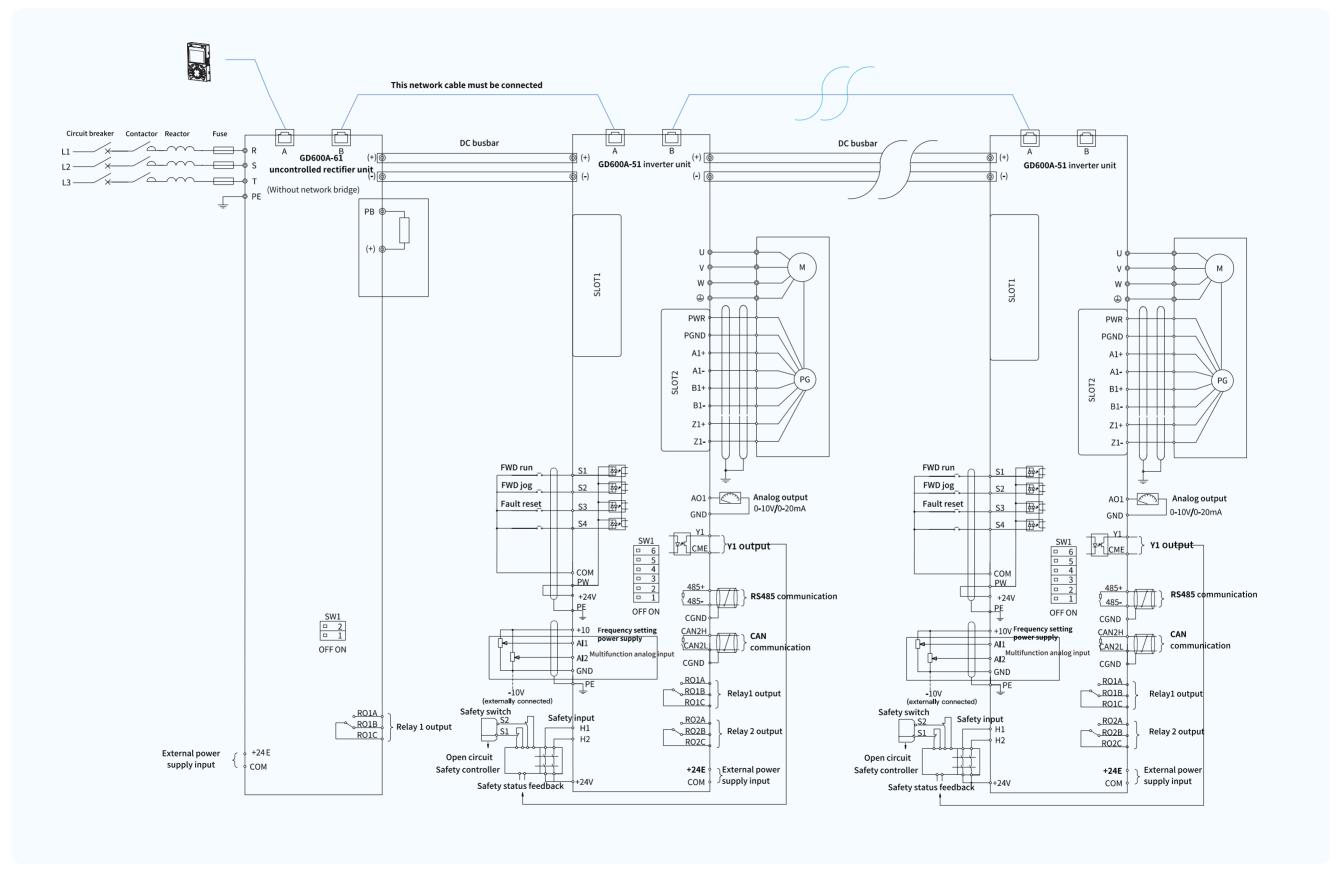
| Parallel configuration | Parallel connection diagram | Required conditions |
|--|-----------------------------|---|
| Double-row layout (multiple rectifiers in parallel) | | I(Rectifier 1)+II(Rectifier 2) \geqslant 0.8*(I1+I2+I3+I4+I5+I6+I7+) I(Rectifier 1)/II(Rectifier 2) \approx (I1+I2+I3+)/(I4+I5+I6+I7+) I1+I2+I3+ \leqslant 350A I4+I5+I6+I7+ \leqslant 350A I5+I6+I7+ \leqslant 200A |
| Single-row layout (rectifier on the left) | | I(Rectifier)≥0.8*(I1+I2+ I3+I4+I5+I6+I7 +I8+I9+I10+I11) I1+I2+I3+I4≤350A I5+I6+I7+≤200A I8+I9+I10≤100A |
| Single-row layout (rectifier on the left) | | $I(\text{Rectifier 1}) + II(\text{Rectifier 2}) \geqslant 0.8*(\text{I1+I2+I3+I4+I5+I6+I7} + \text{I8+I9+I10} + \text{I11+I2+I3})$ $I1+I2+I3+I4 \leqslant 350A$ $I5+I6+I7 \leqslant 350A$ $I8+I9+I10 \leqslant 200A$ $I11+I12+I13 \leqslant 100A$ |

/ Semi-controlled rectifier unit wiring diagram

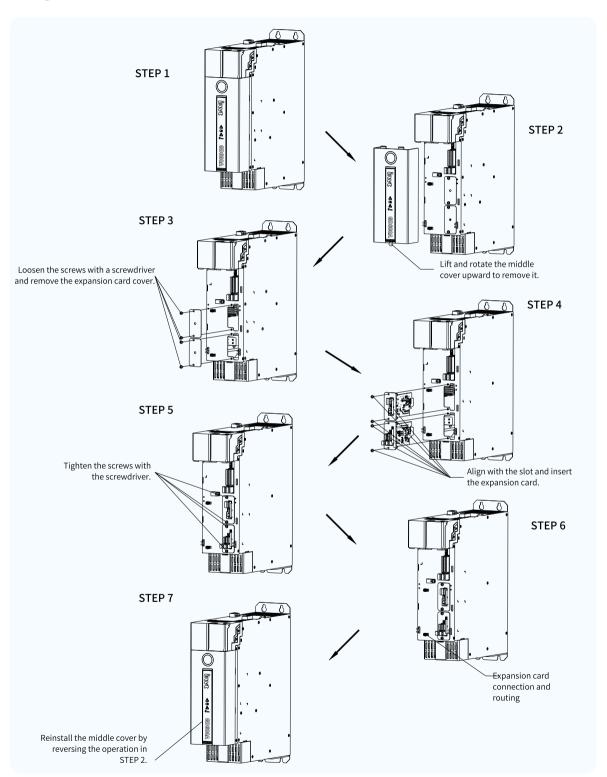


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/ Uncontrolled rectifier unit wiring diagram



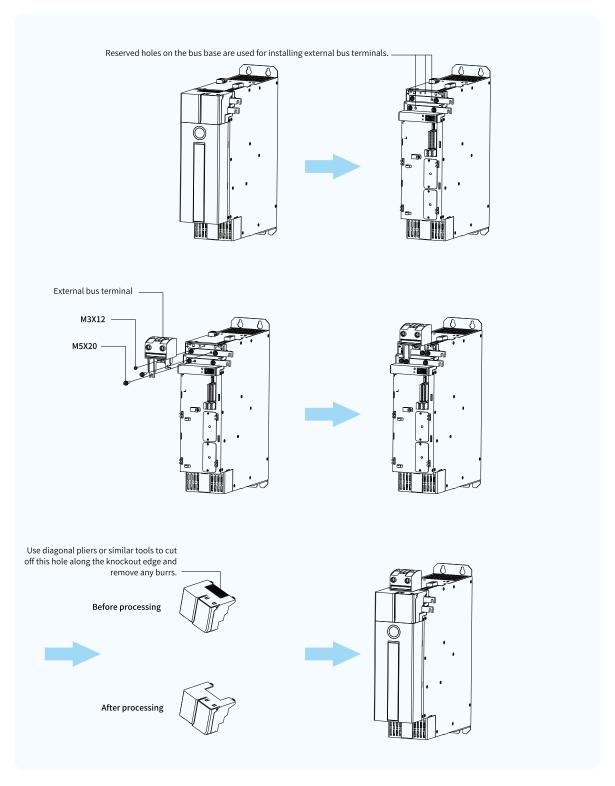
Expansion card installation illustration



Note:

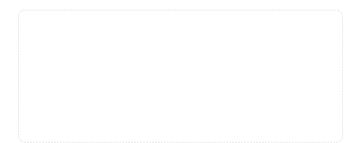
- 1. Ensure that no power is applied before installing the expansion card.
- 2. The expansion card can be installed in any one of the SLOT1 and SLOT2 card slots.
- 3. If interference occurs on the external wires after the expansion card is installed, change the installation slot flexibly to facilitate the wiring. For example, since the connector of the DP card connection cable is large, you are recommended to install the card in SLOT1.

External bus terminal installation illustration



Note: Please tighten screws with proper torque: For M3: 5–6 kgf \cdot cm; For M5: 25–28 kgf \cdot cm

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